

# Types for Information Flow Analysis

## The confinement problem (Lampson, 1973)

- Information systems (computers) run *multiple* processes,
- on behalf of *multiple* users,
- which read and write *multiple* bodies of data.

It is often desirable to control the *flow* of information through these systems, so as to preserve data *secrecy* or *integrity*.

## Access control

- *Access control*, a widespread, authentication-based mechanism,
- only restricts the *initial* release of data.
- Thus, it requires *trust*, which is often misplaced,
- especially concerning *programs*.

## Information flow control

- In the *absence* of trust,
- one must *check* that all flows of information are acceptable,
- which requires a notion of *flow*,
- a security *policy*,
- and an *automated* information flow analysis.

## “System-wide” information flow control

- Computer systems are *non-deterministic*, *concurrent*,
- *interact* with peripheral devices, networks, users,
- whose behavior *cannot* be analyzed beforehand,
- are *observable* through physical means: *time*, *power* consumption.

## Language-based information flow control

- A program written in a *deterministic*, *sequential* language,
- does not interact, except by receiving *input* and producing *output*,
- can be analyzed *before* being run,
- has a well-defined, abstract *semantics*.

## Why begin with language-based security?

- It is *much* easier.
- It *must* be a component of “system-wide” security, lest processes be viewed as “black boxes”.
- By enriching the programming language at hand, it may be possible to ultimately *reconcile* the two approaches.

## Defining information flow

When does a statement  $S$  cause information to *flow* from  $x$  to  $y$ ? Several definitions can be proposed:

- when  $S$  causes the conditional *entropy* of  $x$ , given  $y$ , to decrease.
- when varying  $x$ 's initial value causes  $y$ 's final value to vary, i.e. when  $y$ 's final value *depends* on  $x$ .
- when  $x$ 's initial value can be *reconstructed* from  $y$ 's final value.

The absence of dependency (i.e. the negation of criterion #2) is called *non-interference* (Goguen and Meseguer, 1982).



## Defining an information flow policy

Bell & LaPadula (1973) and Denning (1975) suggest adopting a security lattice  $(\mathcal{L}, \leq)$ , and assigning a label  $\underline{x}$  to every variable  $x$  (or, more generally, to every *piece* of input and output). Then, a flow  $x \rightarrow y$  is acceptable iff  $\underline{x} \leq \underline{y}$ .

Sample lattices:

- $\{\text{L}, \text{H}\}$  allows distinguishing public vs. secret (or trusted vs. untrusted) data.
- The *powerset* of a set of principals allows telling who may consult (or who produced) a piece of data.
- Taking the *product* of several such lattices allows forming composite policies, such as the military classification lattice.

## Specifying a program

Given the lattice  $\{\text{L} \leq \text{H}\}$ , the assertion

$$P : \text{int}^{\text{L}} \times \text{int}^{\text{H}} \rightarrow \text{int}^{\text{L}} \times \text{int}^{\text{H}}$$

claims that  $P$ 's first output does not depend on its second input:

$$\forall k, k_1, k_2 \quad \text{fst} (P (k, k_1)) = \text{fst} (P (k, k_2))$$

Such specifications

- *rely upon* and *enrich* the original type structure;
- *encode* non-interference assertions.

## Specifying a program, more abstractly

Denning (1975) points out that the same non-interference assertion can be encoded in a more polymorphic, lattice-independent manner:

$$P : \forall \ell, h [\ell \leq h]. \text{int}^\ell \times \text{int}^h \rightarrow \text{int}^\ell \times \text{int}^h$$

This emphasizes the fact that information flow analysis is a *pure* dependency analysis.

## A brief (incomplete) history of language-based information flow control

- Denning (1975-1982): imperative language with polymorphic, recursive first-order procedures. No correctness proof.
- Banâtre, Bryce and Le Métayer (1994); Volpano and Smith (1997): imperative language without procedures.
- Palsberg and Ørnbæk (1995): pure  $\lambda$ -calculus. No correctness proof.
- Heintze and Riecke (1998), Abadi, Banerjee, Heintze and Riecke (1999), Pottier and Conchon (2000): purely functional language with data structures.
- Myers (1999): analysis of Java, with dynamic aspects. No correctness proof.
- Pottier and Simonet (2002): functional language with references and exceptions (ML).

## Outline

1. Abadi *et al.*'s **PER**-based approach;
2. Pottier and Conchon's **translation**-based approach;
3. An overview of **Denning's** analysis;
4. Pottier and Simonet's **direct, syntactic** approach.

Non-interference is not a **safety** property: it requires **relating** two processes in execution. How does one attack it? What is the meaning of security annotations, i.e. how does the interpretation of  $\text{int}^L$  differ from that of  $\text{int}^H$ ?

## The *dependency core calculus* (DCC)

A call-by-name  $\lambda$ -calculus with products and sums, extended with two constructs that allow *marking* a value and *using* such a value.

$$\begin{array}{lcl} e & ::= & x \mid \lambda x. e \mid e e \mid \dots \mid \text{mark } e \mid \text{use } x = e \text{ in } e \\ t & ::= & t \rightarrow t \mid \text{unit} \mid t + t \mid t \times t \mid H(t) \end{array}$$

(For simplicity, take  $\mathcal{L} = \{\text{L} \leq \text{H}\}$ .) In the operational semantics, these constructs are no-ops.

Proposed by Abadi, Banerjee, Heintze and Riecke (1999), drawing on existing ideas from binding-time analysis.

## Typing DCC

The typing rules keep track of marks.

$$\begin{array}{c}
 \text{MARK} \\
 \hline
 \Gamma \vdash e : t \\
 \hline
 \Gamma \vdash \text{mark } e : H(t)
 \end{array}
 \qquad
 \begin{array}{c}
 \text{USE} \\
 \hline
 \Gamma \vdash e_1 : H(t_1) \quad \Gamma; x : t_1 \vdash e_2 : t_2 \quad \triangleleft t_2 \\
 \hline
 \Gamma \vdash \text{use } x = e_1 \text{ in } e_2
 \end{array}$$

Every use of a value of marked type must produce a value of *protected* type, a slight generalization:

$$\begin{array}{c}
 \triangleleft H(t) \\
 \hline
 \triangleleft t_1 \rightarrow t_2
 \end{array}
 \qquad
 \begin{array}{c}
 \triangleleft t_2 \\
 \hline
 \triangleleft t_1 \rightarrow t_2
 \end{array}
 \qquad
 \begin{array}{c}
 \triangleleft t_1 \quad \triangleleft t_2 \\
 \hline
 \triangleleft t_1 \times t_2
 \end{array}$$

If  $t$  is protected, then it is *isomorphic* to  $H(t)$ , as we will see.

## PER Basics

A *partial equivalence relation* on  $A$  is a symmetric, transitive relation on  $A$ . It can be viewed as an equivalence relation on a subset of  $A$ , formed of those elements  $x \in A$  such that  $x R x$  holds.

We write  $x : R$  for  $x R x$ . We write  $R \rightarrowtail R'$  for the relation defined by

$$f (R \rightarrowtail R') \iff (\forall x, y \quad x R y \Rightarrow f(x) R' g(y)).$$



## A model of DCC

Consider the category where

- an *object*  $t$  is a cpo  $|t|$  equipped with a PER, also written  $t$ .
- a *morphism* from  $t$  to  $u$  is a continuous function  $f$  such that  $f : t \multimap u$ .

The relation  $t$  specifies a low-level observer's *view* of  $t$ : it groups values of type  $t$  into classes whose elements must not be distinguished by such an observer.

The condition on morphisms is the *non-interference* statement associated with the type  $t \rightarrow u$ .

For instance, consider the flat cpo  $\text{bool} = \{\text{true}, \text{false}\}$ . Define the objects  $\text{boolL}$  and  $\text{boolH}$  by equipping  $\text{bool}$  with the diagonal relation (resp. the everywhere true relation). Then, the assertion

$$f : \text{boolH} \rightarrow \text{boolL}$$

is syntactic sugar for

$$\forall x, y \in \text{bool} \quad x \text{ boolH } y \Rightarrow f(x) \text{ boolL } f(y)$$

that is,

$$\forall x, y \in \text{bool} \quad f(x) = f(y)$$

i.e. requires  $f$  to be a *constant* function.

## Interpreting types

The function type  $t \rightarrow u$  is interpreted as the space of continuous functions from  $|t|$  to  $|u|$ , equipped with the relation  $t \twoheadrightarrow u$ . (That is, two functions are indistinguishable to a low-level observer if they map indistinguishable inputs to indistinguishable outputs.)

The marked type  $H(t)$  is interpreted as the cpo  $|t|$ , equipped with the *everywhere true* relation. (That is, a low-level observer must not be able to distinguish values of a marked type.)

**Lemma.** If  $\triangleleft t$ , then  $t$  and  $H(t)$  are isomorphic.

In other words, a low-level observer's view of a protected type is the everywhere true relation.

## Interpreting expressions

Interpreting MARK boils down to

**Lemma.** If  $e : t$ , then  $e : H(t)$ .

Interpreting USE requires checking

**Lemma.** If  $e : t_1 \rightarrow t_2$  and  $\triangleleft t_2$ , then  $e : H(t_1) \rightarrow t_2$ .

*Proof.* Because  $t_2$  is protected, we have  $\forall x, y \ (ex) \ t_2 \ (ey)$ . So, *a fortiori*,  $\forall x, y \ x \ H(t_1) \ y \Rightarrow (ex) \ t_2 \ (ey)$  holds. This is  $e \ (H(t_1) \rightarrow t_2) \ e$ , that is,  $e : H(t_1) \rightarrow t_2$ .

The fact that this category is a *model* of DCC shows that every program satisfies the *non-interference* assertion encoded within its type. The PER approach gives *direct* meaning to annotated types.

## Full DCC

Full DCC has one “mark” type constructor, written  $T_\ell$ , per security level  $\ell \in \mathcal{L}$ .  $\ell \triangleleft T_{\ell'}(t)$  holds iff  $\ell \leq \ell'$ .

$$\text{USE} \quad \frac{\Gamma \vdash e_1 : T_\ell(t_1) \quad \Gamma; x : t_1 \vdash e_2 : t_2 \quad \ell \triangleleft t_2}{\Gamma \vdash \text{use } x = e_1 \text{ in } e_2}$$

A “homogeneous” type system, such as that of Heintze and Riecke (1998), is easily translated down to full DCC:

$$(t_1 \rightarrow t_2)^\ell \equiv T_\ell(t_1 \rightarrow t_2) \quad (t_1 \times t_2)^\ell \equiv T_\ell(t_1 \times t_2) \quad (t_1 + t_2)^\ell \equiv T_\ell(t_1 + t_2)$$

Subtyping is translated into *coercions* programmed using `mark` and `use`. Thus, DCC can also be seen as a *vehicle* for proving other systems correct.

## The *labelled calculus* approach

Compose a *dynamic* dependency analysis with a *static* type checker.

- The former can be expressed as an *instrumented* semantics.
- Then, interfacing it with the latter requires a *translation*.
- The latter is viewed as a *black box*, yielding a modular proof.
- This suppresses the need to *guess* what the typing rules should be.

Proposed by Pottier & Conchon (2000).

The *labelled calculus* approach

## Defining the labelled calculus

Following Abadi, Lampson & Lévy (1996).

$$e ::= x \mid \lambda x.e \mid (e \ e) \mid \text{let } x = e \text{ in } e \mid \dots \mid \textcolor{blue}{l} : \textcolor{blue}{e} \quad (l \in \mathcal{L})$$

Operational semantics:

$$(l : e_1) \ e_2 \ \rightarrow \ l : (e_1 \ e_2) \quad (\textit{lift})$$

For instance,

$$(\text{L} : (\lambda xy.y)) \ (\text{H} : 27) \rightarrow \text{L} : ((\lambda xy.y) \ (\text{H} : 27)) \rightarrow \text{L} : (\lambda y.y)$$

The *labelled calculus* approach

Defining the labelled calculus

## The meaning of labels: *stability*

*Prefaces* are defined by augmenting expressions with a hole  $\_$ . Write  $e \preceq e'$  if  $e$  is obtained from  $e'$  by replacing some sub-terms with holes.

**Monotonicity.** Let  $e, e'$  be prefixes such that  $e \preceq e'$ . If  $f$  is an expression such that  $e \rightarrow^* f$ , then  $e' \rightarrow^* f$ .

Let  $[e]$  be the prefix of  $e$  where every sub-term labelled  $H$  has been pruned.

(Still assuming  $\mathcal{L} = \{L \leq H\}$ .)

**Stability.** Assume  $e$  is a prefix and  $f$  is an expression. If  $e \rightarrow^* f$  and  $[f] = f$ , then  $[e] \rightarrow^* f$ .

The labelled calculus approach

The meaning of labels: *stability*



## Defining the translation

A *translation* must map the labelled  $\lambda$ -calculus into a more standard  $\lambda$ -calculus.

- A labelled value is mapped to a *pair* of the value and its label.
- For homogeneity, every value should carry exactly *one* label, which requires *joining* multiple labels, exploiting the fact that  $\mathcal{L}$  is a lattice.

The target calculus must have label constants, and a *join* operation:

$$l @ m \rightarrow l \sqcup m \quad (\textit{join})$$

## Translation

$$\llbracket k \rrbracket = (k, \perp)$$

$$\llbracket x \rrbracket = x$$

$$\llbracket \lambda x. e \rrbracket = (\lambda x. \llbracket e \rrbracket, \perp)$$

$$\begin{aligned} \llbracket e_1 \ e_2 \rrbracket &= \text{open } \llbracket e_1 \rrbracket \text{ as } (x, t) \text{ in} \\ &\quad \text{open } x \llbracket e_2 \rrbracket \text{ as } (y, u) \text{ in} \end{aligned}$$

$$(y, t @ u)$$

$$\llbracket \text{let } x = e_1 \text{ in } e_2 \rrbracket = \text{let } x = \llbracket e_1 \rrbracket \text{ in } \llbracket e_2 \rrbracket$$

$$\begin{aligned} \llbracket l : e \rrbracket &= \text{open } \llbracket e \rrbracket \text{ as } (x, t) \text{ in} \\ &\quad (x, l @ t) \end{aligned}$$

## Correctness of the translation

**Simulation.** If  $e \rightarrow f$ , then  $\llbracket e \rrbracket$  reduces to  $\llbracket f \rrbracket$ , modulo an *administrative* congruence, whose axioms include:

$$\begin{aligned} (\text{fst } e, \text{snd } e) &\equiv e \\ (e_1 @ e_2) @ e_3 &\equiv e_1 @ (e_2 @ e_3) \\ \perp @ e &\equiv e \end{aligned}$$

## Axiomatizing a type system for the target calculus

For the sake of modularity, we view a type system as an (opaque) set of *types*, together with a relation between (closed) expressions and types, written  $e : t$ .

Among our requirements are

- Reduction and administrative congruence preserve types.
- Every well-typed, irreducible expression is a value.
- Labels are types;  $l : l'$  implies  $l \leq l'$ .
- There is a type `int`. A value satisfies  $v : \text{int}$  iff it is an integer constant.
- There is a type function  $\times$  such that  $(e, f) : t \times u$  iff  $e : t$  and  $f : u$ .

The *labelled calculus* approach

Axiomatizing a type system for the target calculus

## Putting it all together

Given a source expression  $e$ , let  $e : t$  hold if and only if  $\llbracket e \rrbracket : t$  holds.

*Subject reduction* is an immediate consequence of the simulation lemma and of our requirements. *Progress* is straightforward.

**Non-interference.** If  $e : \text{int} \times \mathbf{L}$  and  $e \rightarrow^* v$ , then  $\llbracket e \rrbracket \rightarrow^* v$ .

*Proof.* Subject reduction yields  $v : \text{int} \times \mathbf{L}$ , that is,  $\llbracket v \rrbracket : \text{int} \times \mathbf{L}$ . Thus,  $v$  must be of the form  $l_1 : l_2 : \dots : l_n : k$ .  $\llbracket v \rrbracket$  must then reduce to  $(k, l_1 \sqcup l_2 \sqcup \dots \sqcup l_n)$ , which implies  $l_1 \sqcup l_2 \sqcup \dots \sqcup l_n$  has type  $\mathbf{L}$ . So, every  $l_i$  is  $\mathbf{L}$ . So,  $\llbracket v \rrbracket$  equals  $v$ , which, by stability, implies  $\llbracket e \rrbracket \rightarrow^* v$ .

**Example: a simply-typed  $\lambda$ -calculus with subtyping**

*Types* are given by

$$\tau ::= \text{int} \mid \tau \rightarrow \tau \mid \tau \times \tau \mid \tau + \tau \mid \textcolor{blue}{l}$$

*Subtyping* extends the ordering on  $\mathcal{L}$ .

$$\begin{array}{c} \text{LABEL} \\ \Gamma \vdash l : l \end{array} \qquad \begin{array}{c} \text{JOIN} \\ \Gamma \vdash e_1 : l_1 \quad \Gamma \vdash e_2 : l_2 \\ \hline \Gamma \vdash e_1 @ e_2 : l_1 \sqcup l_2 \end{array}$$

One checks that this type system meets all of our requirements.

The *labelled calculus* approach

Example: a simply-typed  $\lambda$ -calculus with subtyping

## Deriving Direct Rules

Compose the translation rules with the typing rules.

$$\begin{array}{c}
 \text{INT} \\
 \Gamma \vdash k : \text{int} \times \perp
 \end{array}
 \qquad
 \begin{array}{c}
 \text{VAR} \\
 \dfrac{\Gamma(x) = \varsigma}{\Gamma \vdash x : \varsigma}
 \end{array}
 \qquad
 \begin{array}{c}
 \text{ABS} \\
 \dfrac{\Gamma; x : \varsigma \vdash e : \varsigma'}{\Gamma \vdash \lambda x. e : (\varsigma \rightarrow \varsigma') \times \perp}
 \end{array}$$

$$\begin{array}{c}
 \text{APP} \\
 \dfrac{\Gamma \vdash e_1 : (\varsigma_2 \rightarrow \tau \times l) \times l' \quad \Gamma \vdash e_2 : \varsigma_2}{\Gamma \vdash e_1 e_2 : \tau \times (l \sqcup l')}
 \end{array}
 \qquad
 \begin{array}{c}
 \text{LABEL} \\
 \dfrac{\Gamma \vdash e : \tau \times l'}{\Gamma \vdash (l : e) : \tau \times (l \sqcup l')}
 \end{array}$$

One may write  $\tau^l$  for  $\tau \times l$  and require all types to be generated by

$$\tau ::= \text{int} \mid \varsigma \rightarrow \varsigma \mid \varsigma \times \varsigma \mid \varsigma + \varsigma \quad \varsigma ::= \tau^l$$

The *labelled calculus* approach

Example: a simply-typed  $\lambda$ -calculus with subtyping

## In short

- The proof is *modular*: it also yields polymorphic, constraint-based type systems.
- The approach is applicable to *other* calculi, e.g. the  $\pi$ -calculus under may-testing equivalence.
- However, the fact that the translation must be very simple *imposes* some design choices (e.g. a homogeneous type system).
- This approach gives an *operational* intuition for the distinction between  $\text{int}^L$  and  $\text{int}^H$ : these types represent integers that carry different labels, in a labelled semantics.



## Denning's static analysis (1975–82)

D. E. Denning addresses a programming language equipped with:

- first-order, recursive, *polymorphic* procedures,
- read-only or read/write parameters and local variables of base or array type,
- assignment, sequence, if, while, goto,
- no global variables, dynamic allocation, or exceptions.

No correctness proof is given.

## Specifying procedures

The set of parameters on which every writable parameter depends must be given.

```

procedure max (x; y; var m { x, y });
begin
  if x > y then m := x else m := y
end;

```

In type-theoretic notation, we would write:

$$\text{max} : \forall x, y, m. (x \leq m, y \leq m) \Rightarrow \text{int}^x \times \text{int}^y \times (\text{int}^m \text{ ref}) \rightarrow \text{unit}$$

The level of local variables must also be declared:

```

procedure swap (var x { y }; var y { x });
var t { x, y };
begin
  t := x; x := y; y := t
end;

```

In type-theoretic notation, we would write:

$$\text{swap} : \forall x, y. (y \leq x, x \leq y) \Rightarrow (\text{int}^x \text{ ref}) \times (\text{int}^y \text{ ref}) \rightarrow \text{unit}$$

or, equivalently,

$$\text{swap} : \forall x. (\text{int}^x \text{ ref}) \times (\text{int}^x \text{ ref}) \rightarrow \text{unit}$$

## Checking procedures

From these declarations, one determines the information level of every expression  $e$ , written  $\underline{e}$ , a subset of the procedure's parameters. Then, one checks that every statement is *secure* (i.e. does not cause leaks).

An assignment  $x := e$  is secure if  $\underline{e} \leq \underline{x}$  (*direct* flow).

A sequence  $S_1; S_2$  is secure if  $S_1$  and  $S_2$  are both secure.

A conditional if  $e$  then  $S$  is secure if

- $S$  is secure;
- for every variable  $x$  that *may* be assigned within  $S$ ,  $\underline{e} \leq \underline{x}$  (*indirect* flow).

A procedure call is secure if flows between formals induce valid flows between actuals.

## Example

The following procedure copies  $x$  into  $y$ , assuming  $x$  is initially 0 or 1.

```
procedure copy (x; var y)
  var z;
begin
  y := 0; z := 0;
  if x = 0 then z := 1;
  if z = 0 then y := 1
end;
```

It is insecure. Its specification should be amended by declaring `var y { x }`,  
`var z { x }`.

The information flow from  $x$  to  $y$ , through  $z$ , is caused by the combined effect of *both* if statements, even though *every* execution skips one of them.

## Towards a generalization: $\underline{pc}$

In Denning's restricted language, the set of variables that may be assigned within a given statement is *known*.

This is no longer true in the presence of, say, first-class references and functions. Thus, Heintze and Riecke (1998) and Myers (1999) *parameterize* the judgement “ $S$  is secure” with an information level, written  $\underline{pc}$ .

An assignment  $x := e$  is secure at  $\underline{pc}$  if  $\underline{pc} \sqcup \underline{e} \leq \underline{x}$ .

A sequence  $S_1; S_2$  is secure at  $\underline{pc}$  if  $S_1$  and  $S_2$  are both secure at  $\underline{pc}$ .

A conditional if  $e$  then  $S$  is secure at  $\underline{pc}$  if  $S$  is secure at  $\underline{pc} \sqcup \underline{e}$ .

$pc$  becomes an additional (implicit) formal parameter to every procedure.

## Information flow inference for ML

We have described analyses for a purely functional language and for a simple imperative language. First-class references are addressed by Heintze and Riecke (1998), exceptions by Myers (1999), albeit only informally. There remains to combine these ideas into a type system that supports type inference, and to prove it correct.

Proposed by Pottier and Simonet (2002).

## Syntax

The language, dubbed ML, has *second-class* exceptions. It restricts certain expression forms to be built out of *values*.

$$\begin{aligned}
 v &::= x \mid () \mid k \mid \lambda x. e \mid m \mid (v, v) \mid \text{inj}_j v \\
 a &::= v \mid \text{raise } \varepsilon v \\
 e &::= a \mid v v \mid \text{ref } v \mid v := v \mid !v \mid \text{proj}_j v \mid v \text{ case } x \succ e e \mid \text{let } x = v \text{ in } e \mid E[e] \\
 E &::= \text{bind } x = [] \text{ in } e \\
 &\quad \mid [] \text{ handle } \varepsilon x \succ e \mid [] \text{ handle } e \text{ done} \mid [] \text{ handle } e \text{ raise} \mid [] \text{ finally } e
 \end{aligned}$$

The semantics is call-by-value.



## Trouble with labels

The statement if  $x = 0$  then  $z := 1$  causes information to flow from  $x$  to  $z$ , even when it is skipped. As a result, designing a labelled semantics becomes problematic.

Instead of using labels and prefixes to reason about arbitrary data:

$$(L : (\lambda xy.y)) (H : -) \rightarrow^* L : (\lambda y.y)$$

which implied  $(\lambda xy.y) \ 27 \rightarrow^* \lambda y.y$  and  $(\lambda xy.y) \ 68 \rightarrow^* \lambda y.y$  by *monotonicity* and *erasure*, we will reason directly about *two* processes that share some structure:

$$(\lambda xy.y) \langle 27 \mid 68 \rangle \rightarrow^* \lambda y.y$$

with the same consequences, this time via *projection*.

## The *bracket calculus*

The language  $\text{ML}^2$  is defined as an extension of ML.

$$\begin{aligned} v &::= \dots \mid \langle v \mid v \rangle \mid \text{void} \\ a &::= \dots \mid \langle a \mid a \rangle \\ e &::= \dots \mid \langle e \mid e \rangle \end{aligned}$$

A  $\text{ML}^2$  term encodes a pair of ML terms. For instance,  $\langle v_1 \mid v_2 \rangle v$  and  $\langle v_1 v \mid v_2 v \rangle$  both encode the pair  $(v_1 v, v_2 v)$ .

Two *projection* functions map a  $\text{ML}^2$  term to the two ML terms which it encodes. In particular,  $[\langle e_1 \mid e_2 \rangle]_i = e_i$ , for  $i \in \{1, 2\}$ .

## Semantics of ML<sup>2</sup>: principles

As in the labelled  $\lambda$ -calculus, each language construct is typically dealt with by *two* reduction rules: a standard one, and one that moves (*lifts*) brackets out of the way. The latter are no-ops w.r.t. the term's projections.

$$(\lambda x.e) \, v \rightarrow e[x \leftarrow v] \quad (\beta)$$

$$\langle v_1 \mid v_2 \rangle \, v \rightarrow \langle v_1 \mid [v]_1 \mid v_2 \mid [v]_2 \rangle \quad (\text{lift-app})$$

$$\text{proj}_j \, (v_1, v_2) \rightarrow v_j \quad (\text{proj})$$

$$\text{proj}_j \, \langle v_1 \mid v_2 \rangle \rightarrow \langle \text{proj}_j \, v_1 \mid \text{proj}_j \, v_2 \rangle \quad (\text{lift-proj})$$

(Slightly simplified versions shown.)

Brackets encode the *differences* between two programs, i.e. their “secret” parts.

The (hypothetical) reduction rule

$$e \rightarrow \langle [e]_1 \mid [e]_2 \rangle,$$

while computationally correct, would cause the type system to view *every* expression as “secret”.

The “lift” rules provide an explicit description of information flow, and must be made as precise as possible.

## Semantics of ML<sup>2</sup>: imperative constructs

The meaning of memory locations is given by a *store*  $\mu$ , i.e. a partial map from memory locations to values – which may contain brackets. Store bindings of the form  $m \mapsto \langle v \mid \text{void} \rangle$  or  $m \mapsto \langle \text{void} \mid v \rangle$  account for situations where the two programs at hand have different allocation patterns.

Reductions which take place inside a  $\langle \cdot \mid \cdot \rangle$  construct must use or affect only one projection of the store. For this purpose, let *configurations* be of the form  $e /_i \mu$ , where  $i \in \{\bullet, 1, 2\}$ . Write  $e / \mu$  for  $e /_\bullet \mu$ .

$$\frac{e_i /_i \mu \rightarrow e'_i /_i \mu' \quad e_j = e'_j \quad \{i, j\} = \{1, 2\}}{\langle e_1 \mid e_2 \rangle / \mu \rightarrow \langle e'_1 \mid e'_2 \rangle / \mu'} \quad (\text{bracket})$$

Define the following auxiliary function:

$$\begin{aligned} \text{update}_{\bullet} v v' &= v' \\ \text{update}_1 v v' &= \langle v' \mid [v]_2 \rangle \\ \text{update}_2 v v' &= \langle [v]_1 \mid v' \rangle \end{aligned}$$

Then, the reduction rules for assignment are:

$$\begin{aligned} m := v /_i \mu &\rightarrow () /_i \mu[m \mapsto \text{update}_i \mu(m) v] && (\text{assign}) \\ \langle v_1 \mid v_2 \rangle := \textcolor{blue}{v} / \mu &\rightarrow \langle v_1 := \textcolor{blue}{[v]}_1 \mid v_2 := \textcolor{blue}{[v]}_2 \rangle / \mu && (\text{lift-assign}) \end{aligned}$$

Analogous rules are given for dynamic allocation and dereferencing.

## Example

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if ! $x = 0$  then  $z := 1$  /  $x \mapsto \langle 0 \mid 1 \rangle, z \mapsto 0$ 
→ if  $\langle 0 \mid 1 \rangle = 0$  then  $z := 1$  /  $x \mapsto \langle 0 \mid 1 \rangle, z \mapsto 0$ 
→ if  $\langle 0 = 0 \mid 1 = 0 \rangle$  then  $z := 1$  /  $x \mapsto \langle 0 \mid 1 \rangle, z \mapsto 0$ 
→ if  $\langle \text{true} \mid \text{false} \rangle$  then  $z := 1$  /  $x \mapsto \langle 0 \mid 1 \rangle, z \mapsto 0$ 
→  $\langle \text{if true then } z := 1 \mid \text{if false then } z := 1 \rangle$  /  $x \mapsto \langle 0 \mid 1 \rangle, z \mapsto 0$ 
→  $\langle () \mid () \rangle$  /  $x \mapsto \langle 0 \mid 1 \rangle, z \mapsto \langle 1 \mid 0 \rangle$ 

```

## Semantics of ML<sup>2</sup>: exceptions

$$\text{bind } x = v \text{ in } e \rightarrow e[x \Leftarrow v] \quad (\text{bind})$$

$$\text{raise } \varepsilon v \text{ handle } \varepsilon x \succ e \rightarrow e[x \Leftarrow v] \quad (\text{handle})$$

$$\text{raise } \varepsilon v \text{ handle } e \text{ done} \rightarrow e \quad (\text{handle-done})$$

$$\text{raise } \varepsilon v \text{ handle } e \text{ raise} \rightarrow e; \text{raise } \varepsilon v \quad (\text{handle-raise})$$

$$a \text{ finally } e \rightarrow e; a \quad (\text{finally})$$

$$E[a] \rightarrow a \quad (\text{pop})$$

*if  $E$  handles neither  $[a]_1$  nor  $[a]_2$*

$$E[\langle a_1 \mid a_2 \rangle] / \mu \rightarrow \langle [E]_1[a_1] \mid [E]_2[a_2] \rangle / \mu \quad (\text{lift-context})$$

*if none of the above rules applies*



## Examples

$\text{bind } x = \langle 3 \mid 4 \rangle \text{ in } (x, 0) \rightarrow (\langle 3 \mid 4 \rangle, 0)$

$\langle 3 \mid 4 \rangle \text{ handle } e \text{ done} \rightarrow \langle 3 \mid 4 \rangle$

$\text{bind } x = \langle 3 \mid \text{raise } \epsilon () \rangle \text{ in } (x, 0)$

$\rightarrow \langle \text{bind } x = 3 \text{ in } (x, 0) \mid \text{bind } x = \text{raise } \epsilon () \text{ in } (x, 0) \rangle$

$\rightarrow^* \langle (3, 0) \mid \text{raise } \epsilon () \rangle$

## Relating $\text{ML}^2$ to ML

**Soundness.** Let  $i \in \{1, 2\}$ . If  $e / \mu \rightarrow e' / \mu'$ , then  $[e / \mu]_i \rightarrow [e' / \mu']_i$ .

**Completeness.** Assume  $[e / \mu]_i \rightarrow^* a_i / \mu'_i$  for all  $i \in \{1, 2\}$ . Then, there exists a configuration  $a / \mu'$  such that  $e / \mu \rightarrow^* a / \mu'$ .

In short, brackets cannot *corrupt* or *block* reduction.

The bracket calculus can now be seen as a tool to attack the non-interference proof, provided we can *control* the proliferation of brackets during reduction.

We will do so using a standard technique: a type system for  $\text{ML}^2$ , together with a *subject reduction* theorem.

## The types of ML<sup>2</sup>

*Types* and *rows* are defined as follows:

$$t ::= \text{unit} \mid \text{int}^\ell \mid (t \xrightarrow{pc \ [r]} t)^\ell \mid t \text{ ref}^\ell \mid t \times t \mid (t + t)^\ell$$

$$r ::= \{\varepsilon \mapsto pc\}_{\varepsilon \in \mathcal{E}}$$

*Subtyping* extends the ordering on information levels.

$$\text{int}^\oplus \quad (\ominus \xrightarrow{\ominus \ [\oplus]} \oplus)^\oplus \quad \odot \text{ ref}^\oplus \quad \oplus \times \oplus \quad (\oplus + \oplus)^\oplus \quad \{\varepsilon \mapsto \oplus\}_{\varepsilon \in \mathcal{E}}$$

The auxiliary predicate  $\ell \triangleright t$  holds if  $\ell$  *guards* (*taints*)  $t$ :

$$\begin{array}{c}
\ell \triangleright \text{unit} \\
\\
\frac{\ell \leq \ell'}{\ell \triangleright \text{int}^{\ell'}} \qquad \frac{\ell \leq \ell'}{\ell \triangleright (* \xrightarrow{* \text{[*]}} *)^{\ell'}} \\
\\
\frac{\ell \leq \ell'}{\ell \triangleright * \text{ref}^{\ell'}} \qquad \frac{\ell \triangleright t_1 \quad \ell \triangleright t_2}{\ell \triangleright t_1 \times t_2} \qquad \frac{\ell \leq \ell'}{\ell \triangleright (* + *)^{\ell'}}
\end{array}$$

## ML<sup>2</sup>'s type system

We distinguish two forms of typing judgements: one deals with values only, the other with arbitrary expressions.

$$\Gamma \vdash v : t$$

$$\textcolor{blue}{pc}, \Gamma \vdash e : t \text{ [}\textcolor{red}{r}\text{]}$$

They are connected via the following typing rule:

$$\frac{\text{E-VALUE} \quad \Gamma \vdash v : t}{*, \Gamma \vdash v : t \text{ [}\ast\text{]}}$$

## Keeping track of brackets

The type system is parameterized over an (upward-closed) set of information levels  $H$ , the “secret” levels. The system guarantees that the type of every bracket is guarded by some level in  $H$ :

$$\text{V-BRACKET} \quad \frac{\Gamma \vdash v_1 : t \quad \Gamma \vdash v_2 : t \quad pc' \in H \quad pc' \triangleleft t}{\Gamma \vdash \langle v_1 \mid v_2 \rangle : t}$$

## Abstraction and application

Abstraction delays effects ( $pc, r$ ); application forces them ( $pc \leq pc'$ ).

$$\begin{array}{c}
 \text{V-ABS} \\
 \hline
 pc, \Gamma[x \mapsto t'] \vdash e : t \quad [r] \\
 \hline
 \Gamma \vdash \lambda x. e : (t' \xrightarrow{pc \ [r]} t)^*
 \end{array}
 \qquad
 \begin{array}{c}
 \text{E-APP} \\
 \Gamma \vdash v_1 : (t' \xrightarrow{pc' \ [r]} t)^\ell \quad \Gamma \vdash v_2 : t' \\
 pc \leq pc' \quad \ell \leq pc' \quad \ell \triangleleft t \\
 \hline
 pc, \Gamma \vdash v_1 v_2 : t \quad [r]
 \end{array}$$

Information about the function may leak through its side effects ( $\ell \leq pc'$ ) or through its result ( $\ell \triangleleft t$ ).

## Imperative constructs

Information encoded within the program counter may leak when writing a variable, forming an indirect flow. We follow Denning's solution ( $pc \triangleleft t$ ). In the presence of first-class references, information about the reference's identity may leak as well ( $\ell \triangleleft t$ ).

$$\text{E-ASSIGN} \quad \frac{\Gamma \vdash v_1 : t \text{ ref}^\ell \quad \Gamma \vdash v_2 : t \quad pc \sqcup \ell \triangleleft t}{pc, \Gamma \vdash v_1 := v_2 : \text{unit} \text{ } [*]}$$



## Raising an exception

The value carried by the exception must have fixed (declared, monomorphic) type  $type_n(\varepsilon)$ .

The amount of information carried by the exception itself is represented by  $pc$  at the point where the exception is raised.

$$\text{E-RAISE} \quad \frac{\Gamma \vdash v : type_n(\varepsilon)}{pc, \Gamma \vdash \text{raise } \varepsilon \ v : * \ [\varepsilon : pc; *]}$$

## Handling a specific exception

The amount of information carried by the exception, namely  $pc_\varepsilon$ , is read off the row associated with  $e_1$ .

The handler's side effects may reveal that an exception was caught ( $pc \sqcup pc_\varepsilon$ ). So may the whole expression's result ( $pc_\varepsilon \triangleleft t$ ).

E-HANDLE

$$\frac{pc \sqcup pc_\varepsilon, \Gamma[x \mapsto \text{typexn}(\varepsilon)] \vdash e_2 : t \quad [\varepsilon : pc'; r] \quad pc_\varepsilon \triangleleft t}{pc, \Gamma \vdash e_1 \text{ handle } \varepsilon x \succ e_2 : t \quad [\varepsilon : pc'; r]}$$

## Computing in sequence

$e_2$ 's side effects may reveal that that  $e_1$  completed successfully, i.e. did not raise *any* exception. The level  $\sqcup r_1$  is used as an approximation of the information disclosed in that case.

E-BIND

$$\frac{pc, \Gamma \vdash e_1 : t' \quad [r_1] \quad pc \sqcup (\sqcup r_1), \Gamma[x \mapsto t'] \vdash e_2 : t \quad [r_2]}{pc, \Gamma \vdash \text{bind } x = e_1 \text{ in } e_2 : t \quad [r_1 \sqcup r_2]}$$

## Finally

An event that *must* occur conveys no information, so  $e_2$ 's side effects are not constrained further than the whole expression's.

$$\frac{\text{E-FINALLY} \quad \begin{array}{c} pc, \Gamma \vdash e_1 : t \quad [r] \\ pc, \Gamma \vdash e_2 : * \quad [\partial \perp] \end{array}}{pc, \Gamma \vdash e_1 \text{ finally } e_2 : t \quad [r]}$$

However,  $e_2$  is required *not* to raise (informative) exceptions. Indeed, observing an exception originally raised by  $e_1$  betrays the fact that  $e_2$  has completed successfully. To avoid keeping track of this fact, we require it to convey no information.

## Results

**Subject reduction.** If  $\vdash e / \mu : t \ [r]$  and  $e / \mu \rightarrow e' / \mu'$  then  $\vdash e' / \mu' : t \ [r]$ .

The type system assigns “high” security levels (i.e. levels in  $H$ ) to values of the form  $\langle v_1 \mid v_2 \rangle$ . By subject reduction, any expression which may reduce to such a value must also carry a “high” annotation. Conversely, no expression with a “low” annotation can produce such a value.

**Lemma.** Let  $\ell \notin H$ . If  $\vdash_H e : \text{int}^\ell$  and  $e \rightarrow^* v$  then  $\lfloor v \rfloor_1 = \lfloor v \rfloor_2$ .

Thus, this approach also gives *operational* meaning to the distinction between  $\text{int}^\text{L}$  and  $\text{int}^\text{H}$ .

## Results

**Non-interference.** Choose  $\ell, h \in \mathcal{L}$  such that  $h \not\leq \ell$ . Let  $h \triangleleft t$ . Assume  $(x \mapsto t) \vdash e : \text{int}^\ell$ , where  $e$  is a ML expression. If, for all  $i \in \{1, 2\}$ ,  $\vdash v_i : t$  and  $e[x \Leftarrow v_i] \rightarrow^* v'_i$  hold, then  $v'_1 = v'_2$ .

*Proof.* Let  $H = \uparrow\{h\}$ . Define  $v = \langle v_1 \mid v_2 \rangle$ . By V-BRACKET,  $\vdash_H v : t$  holds. A substitution lemma yields  $\vdash_H e[x \Leftarrow v] : \text{int}^\ell$ . Now,  $[e[x \Leftarrow v]]_i$  is  $e[x \Leftarrow v_i]$ , which, by hypothesis, reduces to  $v'_i$ . By *completeness*, there exists an answer  $a$  such that  $e[x \Leftarrow v] \rightarrow^* a$ . Then, by *soundness*, we have  $[a]_i = v'_i$  for all  $i \in \{1, 2\}$ , which implies that  $a$  is a value. Lastly,  $h \not\leq \ell$  yields  $\ell \notin H$ . The result follows by the previous lemma.

## Type inference

The type system presented so far is *ground*. We can build, on top of it, a type system with *type variables*, *finite syntax* for rows and type schemes, and *constraints*.

$$\begin{array}{ll}
 \tau & ::= \beta \mid \mathbf{unit} \mid \mathbf{int}^\lambda \mid (\tau \xrightarrow{\pi [\rho]} \tau)^\lambda \mid \tau \mathbf{ref}^\lambda \mid \tau \times \tau \mid (\tau + \tau)^\lambda \\
 \rho & ::= \gamma \mid (\varepsilon : \lambda; \rho) \mid \partial \lambda \\
 \lambda, \pi & ::= \delta \mid \ell \\
 C & ::= \mathbf{true} \mid \mathbf{false} \mid C \wedge C \mid \exists \alpha. C \\
 & \mid \tau \leq \tau \mid \rho \leq \rho \mid \lambda \leq \lambda \\
 & \mid \lambda \triangleleft \tau
 \end{array}$$

Type inference reduces to *constraint solving*.



## Examples

The usual ML definition of lists:

$$\beta \text{ list} = \text{unit} + (\beta \times \beta \text{ list})$$

must be decorated:

$$\beta \text{ list}^\delta = (\text{unit} + (\beta \times \beta \text{ list}^\delta))^\delta$$

```

let rec length = function
  | []      -> 0
  | _ :: l -> 1 + length l

val length:  $\forall \beta \delta. \beta \text{list}^\delta \rightarrow \text{int}^\delta$ 

let rec iter f = function
  | []      -> ()
  | x :: l -> f x; iter f l

```

```

val iter:  $\forall [\delta_1 \sqcup \delta_2 \sqcup \delta_3 \sqcup (\sqcup \gamma)] \leq \delta]. (\beta \xrightarrow{\delta [\gamma]} \text{unit})^{\delta_1} \rightarrow \beta \text{list}^{\delta_2} \xrightarrow{\delta_3 [\gamma]} \text{unit}$ 

```

$$\forall [\sqcup \gamma \leq \delta]. (\beta \xrightarrow{\delta [\gamma]} \text{unit})^\delta \rightarrow \beta \text{list}^\delta \xrightarrow{\delta [\gamma]} \text{unit}$$

## Language-based information flow control?

- 25 years old,
- stirs much interest,
- *never* put into practice so far!
- *is* it feasible?

Language-based information flow control?

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